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(chapter II). This example can be used as a basis for all new users of the Sepro MPA-II control unit who wish to create programs. I – 1. Description of the robot cycle The cycle described in the example is an IMM unloading application with a single part release on a conveyor belt. S E P R O E P R O Y = 250 Y = 100 X = 150 X = 1400 Z = 850 Z ...

MPA-II v2 ZN - ZS Robots Software version 1

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know the Sepro language, access the program using the S900-II editor. (See User Manual for the modifications). To define the point markers, you must first analyse the robot's cycle to see where the points should be (See figure 1 : page 1). These points may refer to one or several moving axes.

S900-II Programming - Level 1 - Conair

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The robot is equipped with an advanced safety system. Depending on the particu-lar characteristics of the robot workspace, the settings for the safety system must be configured to guarantee the safety of all personnel and equipment around the robot. Applying settings defined by the risk assessment is the first thing the integrator must do.

PolyScope Manual - United States Naval Academy

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