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mechanism for  
designing a feedback  
which gives reasonable  
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variables*** Introduction  
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***L3.2 - Discrete-time  
optimal control over  
a finite horizon as  
an optimization***

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***Lecture 20 (Optimal  
Control in Linear  
Systems)*** Learning  
Theory (Reza

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Shadmehr, PhD)

**Optimal** feedback  
**control** of linear  
dynamical **systems**  
with and without  
additive noise.

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Control, Guidance  
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***Introduction to  
Linear Quadratic  
Regulator (LQR)  
Control*** In this video  
we introduce the linear  
quadratic regulator

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Main Solution

(LQR) **controller**. We show that an LQR **controller** is a full state feedback ...

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### ***Linear Quadratic***

### ***Regulator (LQR) -- I***

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